# Lecture 4: Amplitude Modulation (Double Sideband *Suppressed Carrier*, DSB-SC)

Prof. Mohammed Hawa Electrical Engineering Department The University of Jordan

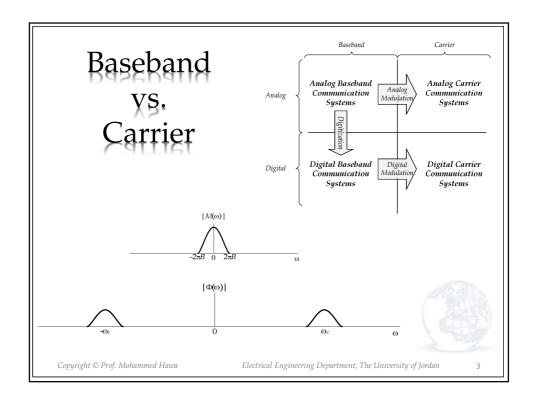
EE421: Communications I

#### Modulation

- Modulation is a process that causes a shift in the frequency spectrum of a message signal m(t) (from baseband to carrier).
- Modulation has advantages.
- Modulation is achieved by varying one of the basic parameters (amplitude, frequency or phase) of a **high-frequency sinusoidal** signal, called the carrier c(t), in proportion to the baseband message signal m(t).

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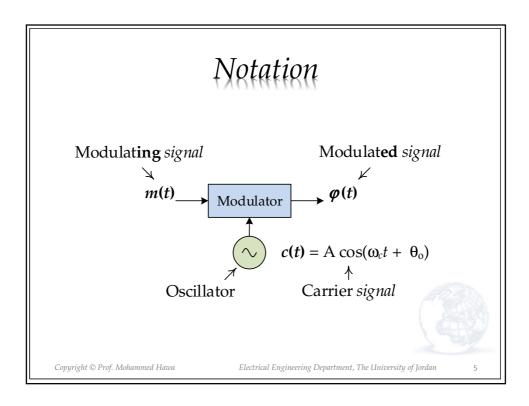


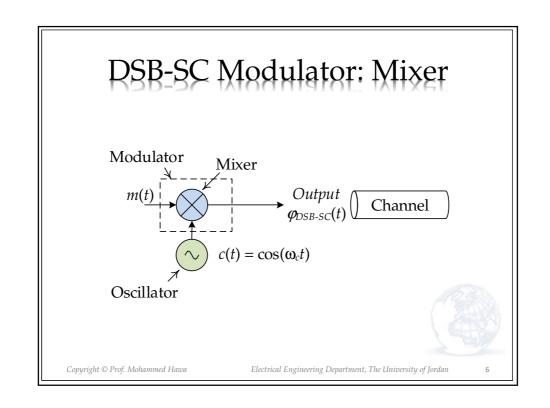
#### Three Modulation Types

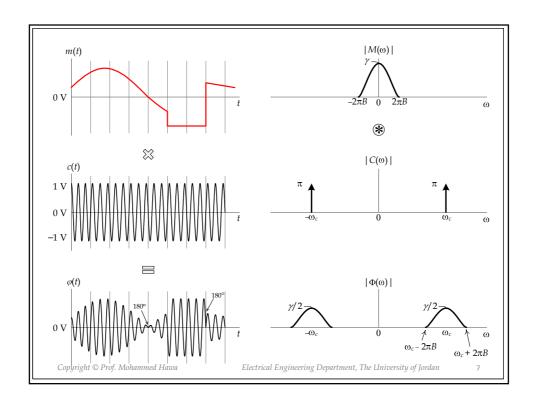
- $A \propto m(t)$ ;  $\omega_c = constant$ ;  $\theta_o = constant$ 
  - Amplitude Modulation (AM)
  - Amplitude Shift Keying (ASK)
- A = constant;  $\omega_c \propto m(t)$ ;  $\theta_o = constant$ 
  - Frequency Modulation (FM)
  - Frequency Shift Keying (FSK)
- A = constant;  $\omega_c = constant$ ;  $\theta_o \propto m(t)$ 
  - Phase Modulation (PM)
  - Phase Shift Keying (PSK)

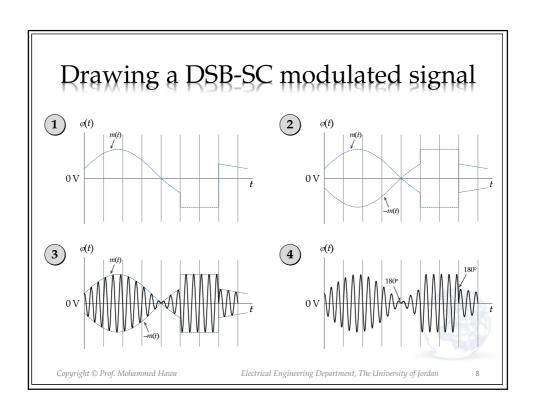


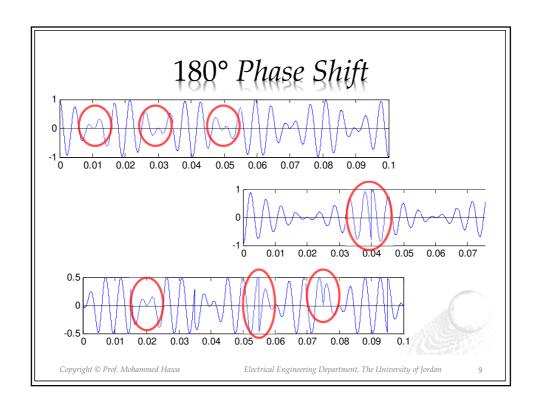
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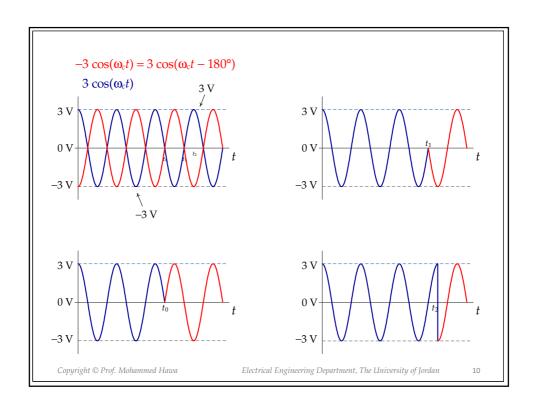


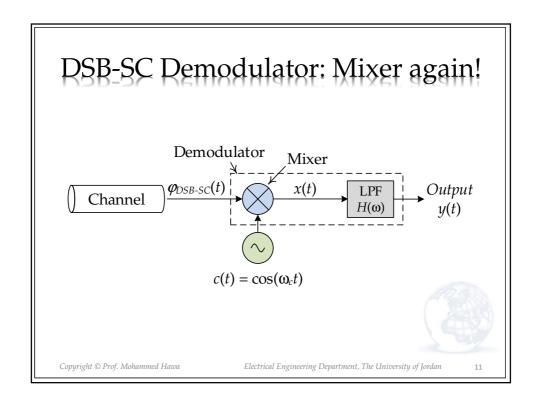


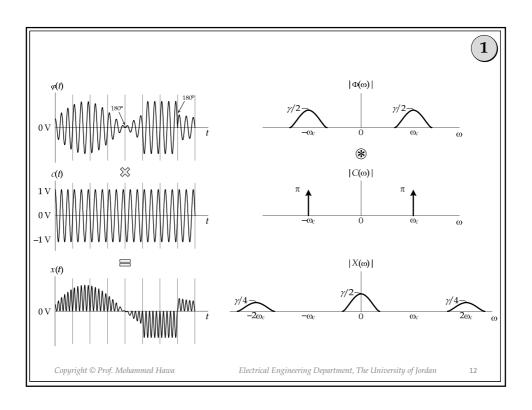


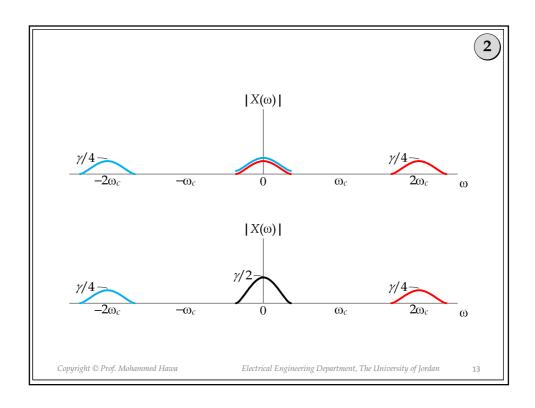


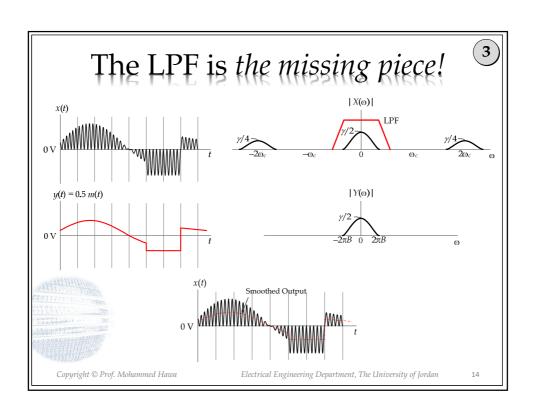




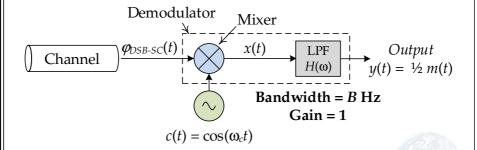








# Filter Specifications!



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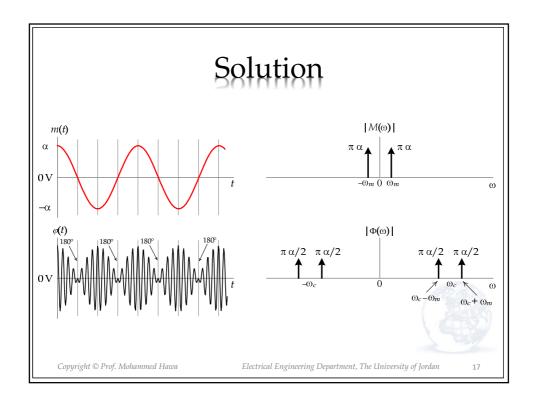
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#### Example

- Assume we perform DSB-SC modulation for the baseband signal  $m(t) = \alpha \cos(\omega_m t)$  [the case of tone modulation], where  $\omega_c >> \omega_m$ :
  - Sketch the **time-domain** modulated signal  $\varphi(t)$ .
  - Sketch the **Fourier transform** of the modulated signal  $\Phi(\omega)$  [frequency domain].
  - Find the **bandwidth** of m(t) and  $\varphi(t)$ .
  - Find the **average power** in both m(t) and  $\varphi(t)$ .
  - Find the **average value** in both m(t) and  $\varphi(t)$ .
  - Show the demodulator hardware.
  - Sketch x(t) and y(t) in the demodulator.

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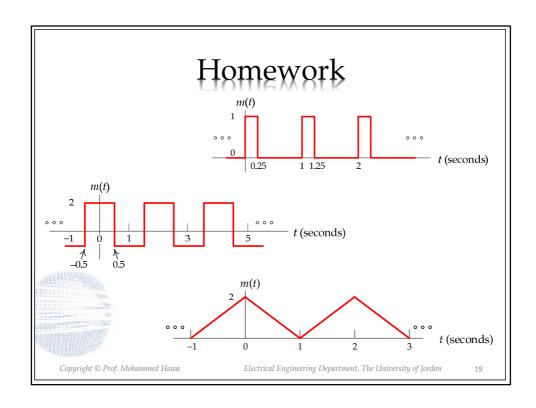
#### Homework

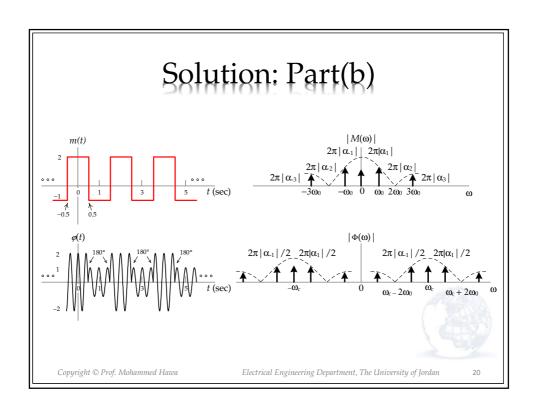
For the following signals m(t):

- Sketch the modulated signal  $\varphi(t)$  at the modulator.
- Are there any sudden 180° phase shifts in  $\varphi(t)$ ? If so, where?
- Sketch the Fourier transform  $\Phi(\omega)$ .
- Sketch the signals x(t) and y(t) at the demodulator.
- Sketch the Fourier transform for  $X(\omega)$  and  $Y(\omega)$ .
- Find the bandwidth for the signals  $\varphi(t)$  and y(t).
- Determine the DC value in m(t),  $\varphi(t)$  and y(t).
- Calculate the average power in m(t),  $\varphi(t)$  and y(t).

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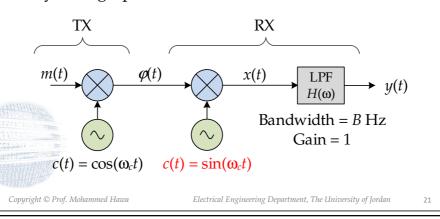
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#### Homework

- For the following circuit, sketch x(t) and y(t), along with the Fourier transform  $X(\omega)$  and  $Y(\omega)$ .
- Try both graphical and mathematical solutions.

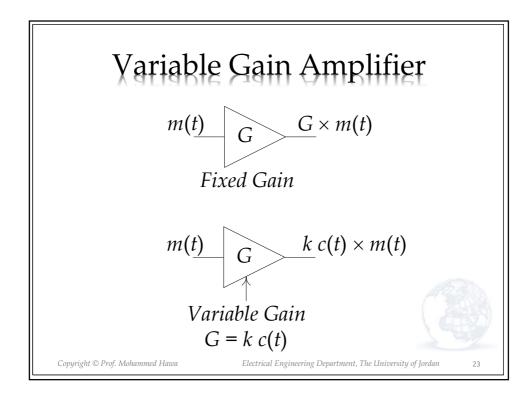


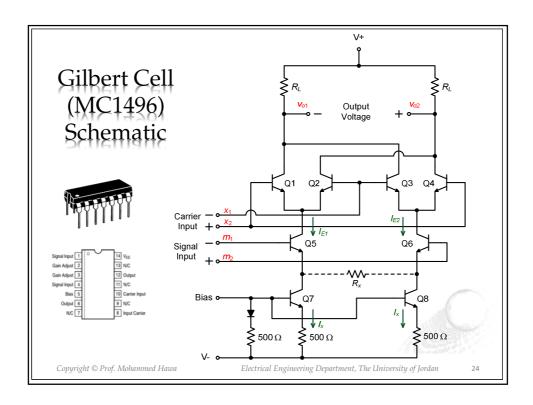
# How to build a *Mixer*?

- Variable Gain Amplifier or Switch
  - The basic design.
- Gilbert Cell (e.g., MC 1496)
  - Popular (used in Integrated Circuits).
  - Built using 8 transistors in a configuration of three variable-gain differential amplifiers.
- Switching Modulator
  - Uses diodes or transistors as switches.
  - Diodes represented cheaper option before ICs, but transistors can be used as well.

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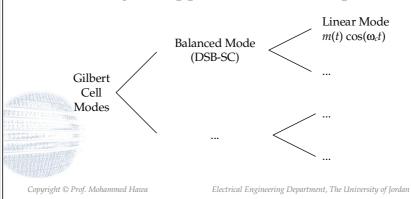
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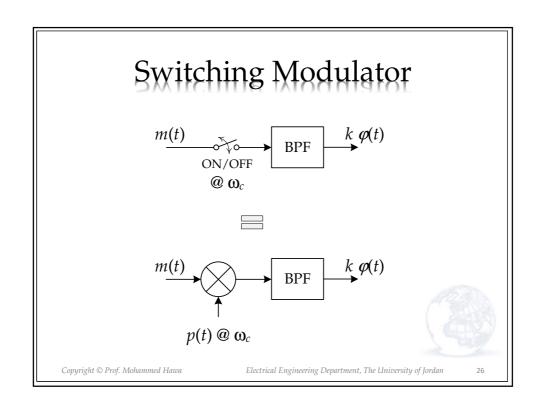


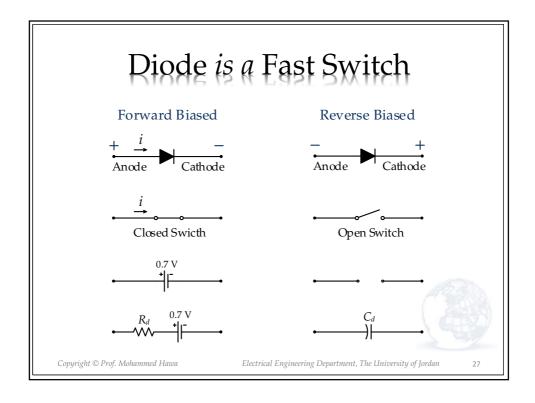


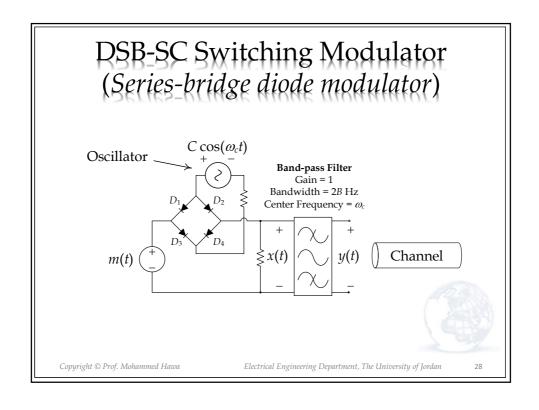
# Gilbert Cell Four Modes

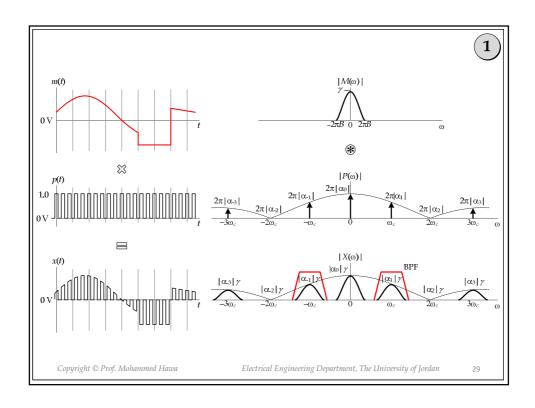
• Gilbert Cell (MC1496) can operate in one of four possible modes based on balancing and/or saturating the upper differential amplifiers.

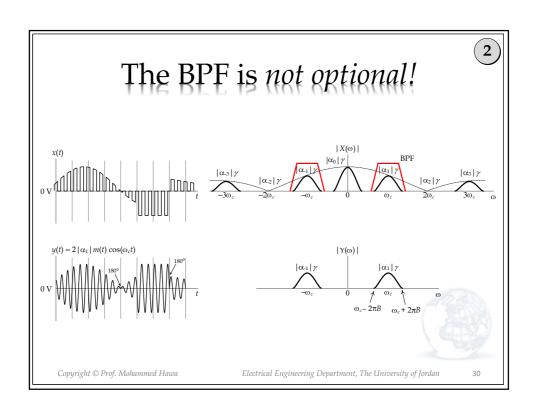


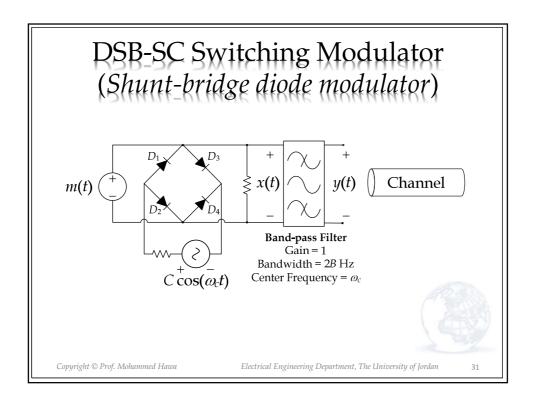


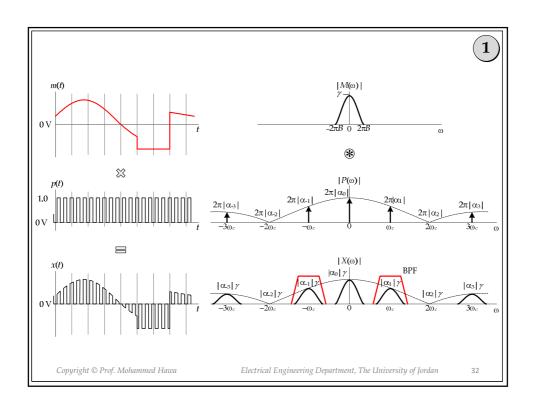


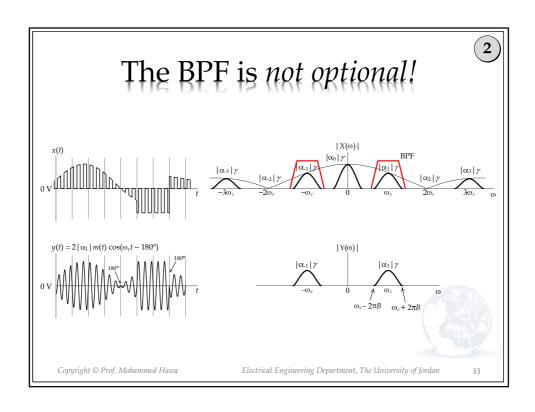


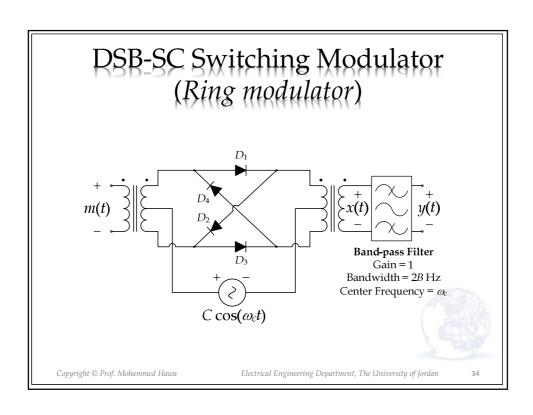


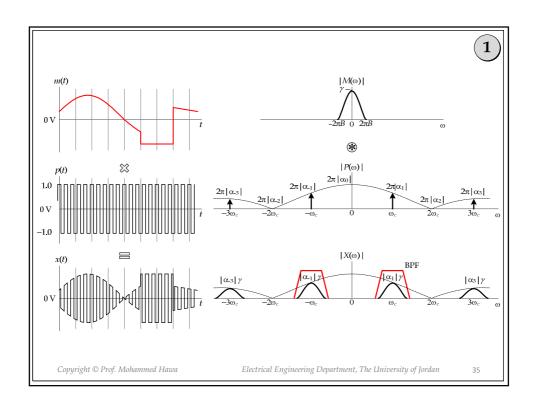


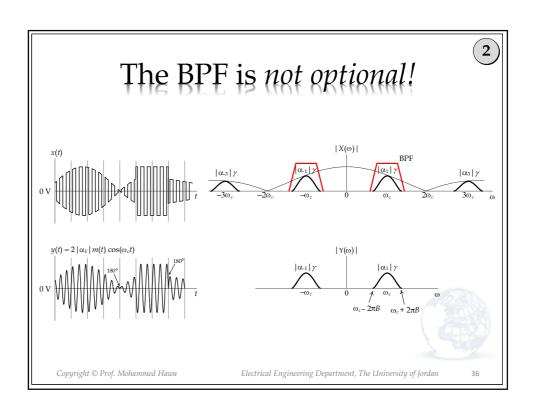






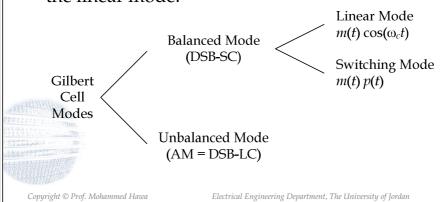


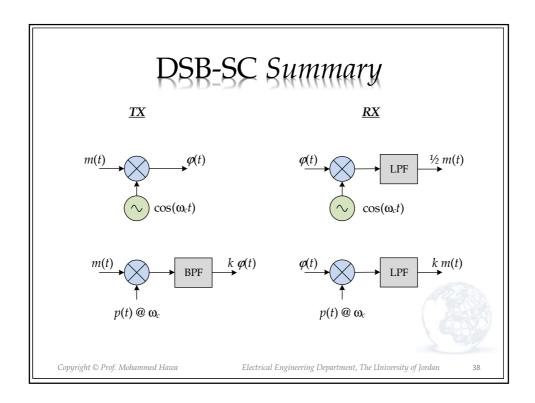




## Gilbert Cell as Switching Modulator

• It is recommended to use the Gilbert Cell (MC1496) in the switching mode, rather than the linear mode.



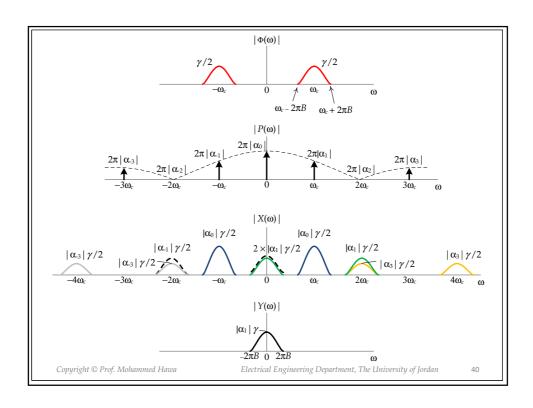


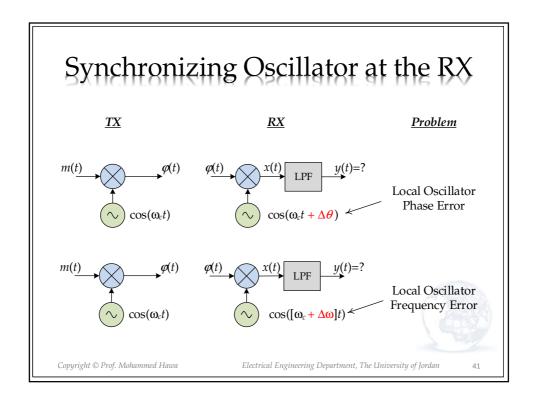
### Homework

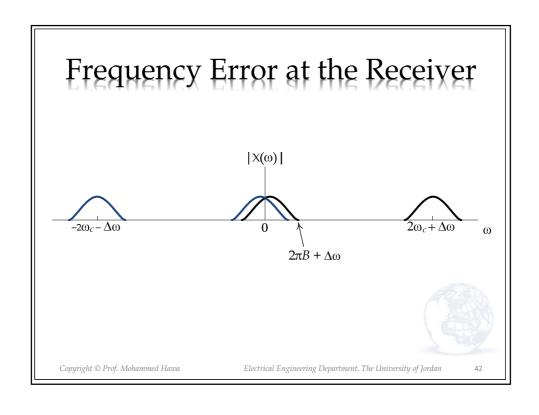
- If we use a switching **de**modulator (say a series-bridge diode demodulator), answer the following:
  - What are the specifications of the filter?
  - What is the value of k in the output y(t) = k m(t) if the input is  $\varphi(t) = m(t) \cos(\omega_c t)$
  - What is the value of k in the output y(t) = k m(t) if the input is  $\varphi(t) = 2 |\alpha_1| m(t) \cos(\omega_c t)$
  - Sketch the Fourier transform of the solution.

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# To avoid problems due to phase and frequency errors

- Solution #1: Use a PLL (Phase-Locked Loop) at the RX. A PLL can, by observing  $\varphi(t)$ , recover the exact frequency and phase of the carrier at the TX, and hence use these values at the RX. The PLL is called a **carrier-recovery circuit** (*complex* and *expensive*). The receiver in this case is known as **synchronous** or **coherent** receiver.
- Solution #2: Do not generate a carrier at the RX. Rather, let the TX send an extra copy of the carrier (e.g., DSB-LC) to help the RX demodulate  $\varphi(t)$ . The RX is known as **asynchronous** or **incoherent** receiver (*cheaper*), but the TX is *power inefficient*.

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